L Number	Hits	Search Text	DB	Time stamp
-	194	(382/152).CCLS.	USPAT; US-PGPUB	2004/03/15 15:34
_	2	WO-9942257-\$.did.	USPAT;	2004/03/15
			US-PGPUB;	15:57
			EPO; JPO; DERWENT	
-	2	WO-9201539-\$.did.	USPAT;	2004/03/15
			US-PGPUB; EPO; JPO;	15:57
			DERWENT	
-	6		USPAT;	2004/03/15
l _	33	4725965.pn. 4985846.pn. 5297238.pn. ((382/152).CCLS.) and robot	US-PGPUB USPAT;	16:09 2004/03/15
	33	((302) 132) . Solls . / and 1020	US-PGPUB	16:54
-	51	((382/151).CCLS.) and robot	USPAT; US-PGPUB	2004/03/15 16:55
_	7	arimatsu-taro.in.	USPAT;	2004/03/15
			US-PGPUB	16:57
-	144	watanabe-atsushi.in.	USPAT; US-PGPUB	2004/03/15 16:57
_	7	382/141-154;901/47.ccls. and	USPAT;	2004/03/15
	61	watanabe-atsushi.in. (robot) same (plural\$3 or multiple or	US-PGPUB USPAT;	16:58 2004/03/15
<del>-</del>	61	dual or two or several or many) adj	US-PGPUB	16:58
	1	(video or camera or CCD or image or		
	1	visual) same (workpiece or work-piece or work adj piece or part or model)		
-	10	((382/154).CCLS.) and (reference or	USPAT;	2004/03/15
		register\$3 or registration or teach\$3 or train\$3 or learn\$3) with (object or model	US-PGPUB	16:59
		or part or workpiece or work-piece or		
	64	work adj piece) same robot (robot) same (video or camera or CCD or	USPAT;	2004/03/15
-	64	image or visual) same (predetermined or	US-PGPUB	16:59
		known or specifi\$2 or determined) near		
_	28	distance   robot same (2-D or two-D or	USPAT;	2004/03/17
		two-dimension\$2 or "2"-dimension\$2 or	US-PGPUB	09:31
		bi-dimensional or (two or "2") adj dimension\$2) with distance		
-	16	robot same (reference or register\$3 or	USPAT;	2004/03/15
		registration or teach\$3 or train\$3 or learn\$3) same (video or camera or CCD or	US-PGPUB	16:59
		image or visual) same (predetermined or		
		known or specifi\$2 or determined) near		
_	62		USPAT;	2004/03/15
		teach\$3 or train\$3 or learn\$3) with	US-PGPUB	16:59
		(model or part or workpiece or work adj		
-	109	(382/153).CCLS.	USPAT; US-PGPUB	2004/03/16 14:00
_	169	(382/\$.ccls. 348/\$.ccls. 356/\$.ccls.	US-PGPUB USPAT;	2004/03/17
		700/\$.ccls. 901/\$.ccls.) and robot\$3 same	US-PGPUB	09:52
		(camera or CCD or imag\$3 or video) same (position\$3 or locat\$4 or (three or "3")		
		adj dimension\$2 or 3D or coordinate) with		
		(orientation or posture or attitude or pose) with (object or workpiece or work		
		adj piece or part or bin or pile\$1 or		
		article or body)	USPAT;	2004/03/17
_	1	("5,617,335").PN.	US-PGPUB	09:52
-	1	("4,727,471").PN.	USPAT;	2004/03/17
	<u> </u>		US-PGPUB	13:55

			_	
-	27	1 = = - 1 = 1	USPAT;	2004/03/17
		video) same (orientation or posture or	US-PGPUB	13:25
		attitude or pose) with (object or		
1		workpiece or work adj piece or part or		
1		bin or pile\$1 or article or body) same		
]		(reference or model or register\$3 or		
		registration or template or stored) with		
		(compar\$5 or match\$3 or correlat\$3 or		
		correspond\$3)		
-	5	JP-05127722-\$.did. JP-07270137-\$.did.	USPAT;	2004/03/18
		JP-07319525-\$.did.	US-PGPUB;	15:21
			EPO; JPO;	
			DERWENT;	
			IBM TDB	